Roy Fox

Assistant Professor of Computer Science University of California, Irvine Intelligent Dynamics Lab 4064 Donald Bren Hall Irvine, CA 92697-3435

☑ royf@uci.edu
③ royf.org
③ Roy Fox
④ @roydfox
④ royf

Appointment

2019-current **Assistant Professor**, *Department of Computer Science*, Donald Bren School of Information and Computer Science, University of California, Irvine

Affiliations: Intelligent Dynamics Lab (indylab) $\[equiverbrack]{C}$ • Center for Machine Learning and Intelligent Systems (CML) $\[equiverbrack]{C}$ • Department of Electrical Engineering and Computer Science (EECS) $\[equiverbrack]{C}$ • HPI Research Center in Machine Learning and Data Science $\[equiverbrack]{C}$ • Center for Theoretical Behavioral Sciences (CTBS) $\[equiverbrack]{C}$ • Algorithms, Combinatorics, and Optimization Center (ACO) $\[equiverbrack]{C}$

Research and Industry Experience

2016–2019 **Postdoctoral Scholar**, *Department of Electrical Engineering and Computer Sciences*, University of California, Berkeley Advisors: Ion Stoica and Ken Goldberg

Affiliations: Real-time Intelligent Secure Explainable Systems (RISELab) ☑ • Automation Lab (AUTOLAB) ☑ • Berkeley Artificial Intelligent Research (BAIR) ☑

- 2012–2013 **Exchange PhD Student**, *Center for Theoretical Neuroscience*, Columbia University Hosts: Larry Abbott and Liam Paninski
 - 2011 Research Intern, Microsoft Research

Education

2017 **PhD**, *School of Computer Science and Engineering*, Hebrew University Advisor: Naftali Tishby

Thesis: Information-Theoretic Methods for Planning and Learning in Partially Observable Markov Decision Processes 🗹

2008 **MS**, *Computer Science Department*, Technion IIT Advisor: Moshe Tennenholtz

Thesis: Reinforcement Learning in Partially Observable Decision Processes 🗹

- 2001 BS (cum laude), School of Computer Science, Hebrew University
- 2000 BS, Medical Sciences, Hebrew University Hadassah Medical School

Grants and Awards

2024–current **NSF CISE: Large**, *Causal Foundations for Decision Making and Learning Role: Senior Personnel*; PI: Elias Bareinboim; award: 2321786; amount: \$5,000,000

2022 Chancellor's Award for Excellence in Undergraduate Research, UCI

- 2020–current **HPI Research Center**, *Machine Learning and Data Science Role: Supervisor*; Director: Erik Sudderth; three fellowships support my students
 - 2020 ICS Research Award: Endeavor, AI for High-Level Computational Science Role: Key Personnel; PI: Eric Mjolsness; amount: \$299,849

- 2018 Workshop sponsorship, Infer to Control workshop at NeurIPS Sponsors: Intel and DeepMind; amount: \$6500
- 2017 Workshop sponsorship, Hierarchical Reinforcement Learning workshop at NeurIPS Sponsor: Intel; amount: \$5000
- 2012–2013 Research scholarship, The Gatsby Charitable Foundation, Columbia University
 - 2011 First place, HUJICode algorithmic programming competition, Hebrew University
 - 1998 Rector award for excellence, Hebrew University

Publications

Conferences

NAACL 2024 Selective Perception: Learning Concise State Descriptions for Language Model Actors

Kolby Nottingham, Yasaman Razeghi, Kyungmin Kim, JB Lanier, Pierre Baldi, **Roy Fox**, and Sameer Singh

Annual Conference of the North American Chapter of the Association for Computational Linguistics

- ICLR 2024 Toward Optimal Policy Population Growth in Two-Player Zero-Sum Games Stephen McAleer, JB Lanier, Kevin Wang, Pierre Baldi, Tuomas Sandholm, and **Roy Fox** 12th International Conference on Learning Representations
- ICML 2023 Do Embodied Agents Dream of Pixelated Sheep?: Embodied Decision Making using Language Guided World Modelling ☑ Kolby Nottingham, Prithviraj Ammanabrolu, Alane Suhr, Yejin Choi, Hannaneh Hajishirzi, Sameer Singh, and Roy Fox

40th International Conference on Machine Learning

- ICML 2023 Learning to Design Analog Circuits to Meet Threshold Specifications Dmitrii Krylov, Pooya Khajeh, Junhan Ouyang, Thomas Reeves, Tongkai Liu, Hiba Ajmal, Hamidreza Aghasi, and **Roy Fox** 40th International Conference on Machine Learning
- ICML 2022 Reducing Variance in Temporal-Difference Value Estimation via Ensemble of Deep Networks ☑

Litian Liang, Yaosheng Xu, Stephen McAleer, Dailin Hu, Alexander Ihler, Pieter Abbeel, and **Roy Fox**

- 39th International Conference on Machine Learning
- RLDM 2022 Learning to Query Internet Text for Informing Reinforcement Learning Agents Kolby Nottingham, Alekhya Pyla, Sameer Singh, and **Roy Fox** 5th Multi-disciplinary Conference on Reinforcement Learning and Decision Making
- AISTATS 2022 Independent Natural Policy Gradient Always Converges in Markov Potential Games **Roy Fox**, Stephen McAleer, Will Overman, and Ioannis Panageas 25th International Conference on Artificial Intelligence and Statistics
- NeurIPS 2021 XDO: A Double Oracle Algorithm for Extensive-Form Games ☑ Stephen McAleer, JB Lanier, Kevin Wang, Pierre Baldi, and **Roy Fox** 35th Conference on Neural Information Processing Systems

| NeurIPS 2020 | Pipeline PSRO: A Scalable Approach for Finding Approximate Nash Equilibria in Large Games ☑ |
|--------------|--|
| | Stephen McAleer, JB Lanier, Roy Fox , and Pierre Baldi 34th Conference on Neural Information Processing Systems |
| SPLASH | AutoPandas: Neural-Backed Generators for Program Synthesis 🗹 |
| OOPSLA 2019 | Rohan Bavishi, Caroline Lemieux, Roy Fox , Koushik Sen, and Ion Stoica 10th ACM SIGPLAN Conference on Systems, Programming, Languages, and Applications: Software for Humanity |
| CASE 2019 | Multi-Task Hierarchical Imitation Learning for Home Automation 🗹 |
| | Roy Fox *, Ron Berenstein*, Ion Stoica, and Ken Goldberg 15th IEEE Conference on Automation Science and Engineering |
| WAFR 2018 | Generalizing Robot Imitation Learning with Invariant Hidden Semi-Markov Models \mathbf{Z} |
| | Ajay Kumar Tanwani, Jonathan Lee, Brijen Thananjeyan, Michael Laskey, Sanjay Krishnan, Roy Fox , Ken Goldberg, and Sylvain Calinon 13th International Workshop on the Algorithmic Foundations of Robotics |
| CASE 2018 | Constraint Estimation and Derivative-Free Recovery for Robot Learning from Demon- |
| 0,02 2010 | strations \mathbf{Z} |
| | Jonathan Lee, Michael Laskey, Roy Fox, and Ken Goldberg |
| | 14th IEEE Conference on Automation Science and Engineering |
| ICML 2018 | RLlib: Abstractions for Distributed Reinforcement Learning 🗹 |
| | Eric Liang*, Richard Liaw*, Robert Nishihara, Philipp Moritz, Roy Fox , Ken Goldberg, Joseph Gonzalez, Michael Jordan, and Ion Stoica 35th International Conference on Machine Learning |
| ICRA 2018 | Fast and Reliable Autonomous Surgical Debridement with Cable-Driven Robots Using a Two-Phase Calibration Procedure 🗹 |
| | Daniel Seita, Sanjay Krishnan, Roy Fox , Stephen McKinley, John Canny, and Ken Goldberg 35th IEEE International Conference on Robotics and Automation |
| ICRA 2018 | Robustly Adjusting Indoor Drip Irrigation Emitters with the Toyota HSR Robot 🗹 |
| | Ron Berenstein, Roy Fox , Stephen McKinley, Stefano Carpin, and Ken Goldberg 35th IEEE International Conference on Robotics and Automation |
| ICLR 2018 | Parametrized Hierarchical Procedures for Neural Programming 🗹 |
| | Roy Fox , Richard Shin, Sanjay Krishnan, Ken Goldberg, Dawn Song, and Ion Stoica 6th International Conference on Learning Representations |
| CoRL 2017 | DDCO: Discovery of Deep Continuous Options for Robot Learning from Demonstrations $\ensuremath{\underline{C}}$ |
| | Sanjay Krishnan*, Roy Fox *, Ion Stoica, and Ken Goldberg 1st Conference on Robot Learning |
| CoRL 2017 | DART: Noise Injection for Robust Imitation Learning 🗹 |
| | Michael Laskey, Jonathan Lee, Roy Fox , Anca Dragan, and Ken Goldberg 1st Conference on Robot Learning |
| CASE 2017 | An Algorithm and User Study for Teaching Bilateral Manipulation via Iterated Best Response Demonstrations 🗹 |
| | Carolyn Chen, Sanjay Krishnan, Michael Laskey, Roy Fox , and Ken Goldberg 13th IEEE Conference on Automation Science and Engineering |

| CASE 2017 | Statistical Data Cleaning for Deep Learning of Automation Tasks from Demonstrations $\underline{\ensuremath{\mathbb{C}}}$ |
|--------------------------|---|
| | Caleb Chuck, Michael Laskey, Sanjay Krishnan, Ruta Joshi, Roy Fox , and Ken Goldberg 13th IEEE Conference on Automation Science and Engineering |
| CDC 2016 | Minimum-Information LQG Control — Part I: Memoryless Controllers 🗹 |
| | Roy Fox and Naftali Tishby 55th IEEE Conference on Decision and Control |
| CDC 2016 | Minimum-Information LQG Control — Part II: Retentive Controllers 🗹 |
| | Roy Fox and Naftali Tishby 55th IEEE Conference on Decision and Control |
| EWRL 2016 | Principled Option Learning in Markov Decision Processes 🗹 |
| | Roy Fox *, Michal Moshkovitz*, and Naftali Tishby 13th European Workshop on Reinforcement Learning |
| UAI 2016 | Taming the Noise in Reinforcement Learning via Soft Updates 🗹 |
| | Roy Fox *, Ari Pakman*, and Naftali Tishby 32nd Conference on Uncertainty in Artificial Intelligence |
| NeurIPS 2013 | A Multi-Agent Control Framework for Co-Adaptation in Brain-Computer Interfaces \blacksquare |
| | Josh Merel*, Roy Fox *, Tony Jebara, and Liam Paninski 27th Annual Conference on Neural Information Processing Systems |
| ICML 2012 | Bounded Planning in Passive POMDPs 🗹 |
| | Roy Fox and Naftali Tishby 29th International Conference on Machine Learning |
| AAAI 2007 | A Reinforcement Learning Algorithm with Polynomial Interaction Complexity for Only-Costly-Observable MDPs 🗹 |
| | Roy Fox and Moshe Tennenholtz 22nd Conference on Artificial Intelligence |
| | Symposia and Workshops |
| FMDM @ NeurIPS 2023 | Selective Perception: Learning Concise State Descriptions for Language Model |
| | Kolby Nottingham, Yasaman Razeghi, Kyungmin Kim, JB Lanier, Pierre Baldi, Roy Fox , and Sameer Singh Foundation Models for Decision Making workshop |
| | Do Embodied Agents Dream of Pixelated Sheep?: Embodied Decision Making using Language Guided World Modelling |
| | Kolby Nottingham, Prithviraj Ammanabrolu, Alane Suhr, Yejin Choi, Hannaneh Hajishirzi, Sameer Singh, and Roy Fox Reincarnating Reinforcement Learning workshop |
| DeepRL @ NeurIPS 2022 | Feasible Adversarial Robust Reinforcement Learning for Underspecified Environments ${\bf \underline{C}}$ |
| | JB Lanier, Stephen McAleer, Pierre Baldi, and Roy Fox Deep Reinforcement Learning workshop |

| RLG | Anytime PSRO for Two-Player Zero-Sum Games 🗹 |
|--------------------------|---|
| @ AAAI 2022 | Stephen McAleer, Kevin Wang, JB Lanier, Marc Lanctot, Pierre Baldi, Tuomas Sandholm, and Roy Fox |
| | Reinforcement Learning in Games workshop |
| DeepRL | Temporal-Difference Value Estimation via Uncertainty-Guided Soft Updates 🗹 |
| @ NeurIPS 2021 | Litian Liang, Yaosheng Xu, Stephen McAleer, Dailin Hu, Alexander Ihler, Pieter Abbeel, and Roy Fox Deep Reinforcement Learning workshop |
| DeepRL @ NeurIPS 2021 | Count-Based Temperature Scheduling for Maximum Entropy Reinforcement Learn- |
| | Dailin Hu, Pieter Abbeel, and Roy Fox Deep Reinforcement Learning workshop |
| DeepRL | Target Entropy Annealing for Discrete Soft Actor–Critic 🗹 |
| @ NeurIPS 2021 | Yaosheng Xu, Dailin Hu, Litian Liang, Stephen McAleer, Pieter Abbeel, and Roy Fox Deep Reinforcement Learning workshop |
| | Obtaining Approximately Admissible Heuristic Functions through Deep Reinforcement Learning and A* Search $\ensuremath{\mathbb{Z}}$ |
| | Forest Agostinelli, Stephen McAleer, Alexander Shmakov, Roy Fox , Marco Valtorta, Biplav Srivastava, and Pierre Baldi Bridging the Gap Between Al Planning and Reinforcement Learning workshop |
| EmbodiedAl | Modular Framework for Visuomotor Language Grounding 🗹 |
| @ CVPR 2021 | Kolby Nottingham, Litian Liang, Daeyun Shin, Charless Fowlkes, Roy Fox , and Sameer Singh Embodied AI workshop |
| RLG | CFR-DO: A Double Oracle Algorithm for Extensive-Form Games 🗹 |
| @ AAAI 2021 | |
| OPTRL | Toward Provably Unbiased Temporal-Difference Value Estimation 🗹 |
| @ NeurIPS 2019 | Roy Fox Optimization Foundations for Reinforcement Learning workshop |
| AMTL | Multi-Task Learning via Task Multi-Clustering 🗹 |
| @ ICML 2019 | Andy Yan, Xin Wang, Ion Stoica, Joseph Gonzalez, and Roy Fox Adaptive and Multitask Learning workshop |
| Infer2Control | Hierarchical Imitation Learning via Variational Inference of Control Programs 🗹 |
| @ NeurIPS 2018 | Roy Fox , Richard Shin, William Paul, Yitian Zou, Dawn Song, Ken Goldberg, Pieter Abbeel, and Ion Stoica |
| | Infer to Control: Probabilistic Reinforcement Learning and Structured Control workshop |
| DLT | An Empirical Exploration of Gradient Correlations in Deep Learning 🗹 |
| @ NeurIPS 2018 | Daniel Rothchild, Roy Fox , Noah Golmant, Joseph Gonzalez, Michael Mahoney, Kai Rothauge, Ion Stoica, and Zhewei Yao Integration of Deep Learning Theories workshop |
| ML for Sys | Neural Inference of API Functions from Input–Output Examples 🗹 |
| @ NeurIPS 2018 | Rohan Bavishi, Caroline Lemieux, Neel Kant, Roy Fox , Koushik Sen, and Ion Stoica Machine Learning for Systems workshop |

| NAMPI | Imitation Learning of Hierarchical Programs via Variational Inference 🗹 |
|----------------|---|
| @ ICML 2018 | Roy Fox *, Richard Shin*, Pieter Abbeel, Ken Goldberg, Dawn Song, and Ion Stoica Neural Abstract Machines and Program Induction workshop |
| PGMRL | Task-Relevant Embeddings for Robust Perception in Reinforcement Learning 🗹 |
| @ ICML 2018 | Eric Liang, Roy Fox , Joseph Gonzalez, and Ion Stoica Prediction and Generative Modeling in Reinforcement Learning workshop |
| Causal Imit. | Robot Learning with Invariant Hidden Semi-Markov Models 🗹 |
| @ RSS 2018 | Ajay Kumar Tanwani, Jonathon Lee, Michael Laskey, Sanjay Krishnan, Roy Fox , and Ken Goldberg Perspectives on Robot Learning: Imitation and Causality workshop |
| DeepRL | Ray RLlib: A Composable and Scalable Reinforcement Learning Library 🗹 |
| @ NeurIPS 2017 | Eric Liang*, Richard Liaw*, Robert Nishihara, Philipp Moritz, Roy Fox , Joseph Gonzalez, Ken Goldberg, and Ion Stoica Deep Reinforcement Learning symposium |
| | Theses |
| 2016 | Information-Theoretic Methods for Planning and Learning in Partially Observable Markov Decision Processes 🗹 |
| | Roy Fox PhD Thesis, Hebrew University |
| 2008 | Reinforcement Learning in Partially Observable Decision Processes 🗹 |
| | Roy Fox MS Thesis, Technion IIT |
| | Preprints |
| 2021 | Improving Social Welfare while Preserving Autonomy via a Pareto Mediator 🗹 |
| | Stephen McAleer, JB Lanier, Michael Dennis, Pierre Baldi, and Roy Fox arXiv:2106.03927 |
| 2021 | A* Search Without Expansions: Learning Heuristic Functions with Deep Q-Networks $\ensuremath{\underline{C}}$ |
| | Forest Agostinelli, Alexander Shmakov, Stephen McAleer, Roy Fox , and Pierre Baldi arXiv:2102.04518 |
| 2019 | Hierarchical Variational Imitation Learning of Control Programs 🗹 |
| | Roy Fox , Richard Shin, William Paul, Yitian Zou, Dawn Song, Ken Goldberg, Pieter Abbeel, and Ion Stoica arXiv:1912.12612 |
| 2017 | Multi-Level Discovery of Deep Options 🗹 |
| | Roy Fox *, Sanjay Krishnan*, Ion Stoica, and Ken Goldberg arXiv:1703.08294 |
| 2015 | Optimal Selective Attention in Reactive Agents 🗹 |
| | Roy Fox and Naftali Tishby arXiv:1512.08575 |
| | |

Talks and Presentations

Invited Talks

- 2024 How Large Models of Image and Text Help Agents to Learn to Behave The Institute for Learning-enabled Optimization at Scale (TILOS), San Diego, March 20
- 2023 Population-Based Competitive Multi-Agent Reinforcement Learning Information Theory and Applications workshop (ITA), San Diego, February 16
- 2023 Population-Based Methods for Single- and Multi-Agent Reinforcement Learning Information Sciences Institute, University of Southern California, January 27
- 2022 Better Together: Population-Based Methods for Single- and Multi-Agent Reinforcement Learning

Department of Electrical and Computer Engineering, Technion IIT, Haifa, Israel, December 29

2020 Structured Control as Inference

Information Theory and Applications workshop (ITA), San Diego, February 7

- 2019 Learning Hierarchical Control Programs
 - University of Michigan, Ann Arbor, April 11
 - University of California, Irvine, March 19
 - O Université de Montréal, Canada, February 22
- 2018 Panel on Inference for Control, moderator

Infer to Control: Probabilistic Reinforcement Learning and Structured Control workshop (Infer2Control @ NeurIPS 2018), Montréal, Canada, December 8

- 2018 Hierarchical Imitation Learning of Robot Skills and Control Programs
 - O Google Research, Tel Aviv, Israel, November 15
 - O Department of Electrical Engineering, Technion IIT, Haifa, Israel, November 14
- 2017 Panel on Hierarchical Reinforcement Learning, moderator

Hierarchical Reinforcement Learning workshop (HRL @ NeurIPS), Long Beach, California, December 9

- 2017 Deep Hierarchical Reinforcement Learning Made Fast and Easy with Ray Data Science Summit (DSS) Europe, Jerusalem, Israel, May 29
- 2016 An Information-Theoretic Bag of Tools for Optimal Control and Reinforcement Learning

Google DeepMind, London, UK, June 1

2016 Minimum-Information Planning in Partially-Observable Decision Problems

Max Planck Institute for Mathematics in the Sciences, Leipzig, Germany, May 10
 University of Stuttgart, Germany, May 9

2015 Soft-Optimal Decisions under Uncertainty

Information and Decision Making workshop (IDeM), University of Hertfordshire, UK, September 3 $\,$

- 2014 Optimal Selective Attention and Action in Reactive Agents
 - O University of California, Berkeley, October 8
 - California Institute of Technology, Los Angeles, October 2
 - University of California, Los Angeles, October 1
 - O University of California, San Diego, September 29
 - O Columbia University, New York, September 24
 - O Microsoft Research, New York, September 16
 - O University of Pennsylvania, Philadelphia, September 15
- 2012 Information Theoretic Methods for POMDP Planning

DARPA MSEE program review meeting, University of California, Los Angeles, May 2

Contributed Talks

2022 MeanQ: Reducing Variance in Temporal-Difference Value Estimation via Ensemble of Deep Networks

ICML spotlight, Baltimore, Maryland, July 21

- 2019 Multi-Task Hierarchical Imitation Learning for Home Automation *CASE*, Vancouver, Canada, August 25
- 2016 Minimum-Information LQG Control CDC double talk, Las Vegas, Nevada, December 14
- 2016 Taming the Noise in Reinforcement Learning via Soft Updates UAI, Jersey City, New Jersey, June 26
- 2012 Bounded Planning in Passive POMDPs ICML spotlight, Edinburgh, UK, June 27
- 2007 A Reinforcement Learning Algorithm with Polynomial Interaction Complexity for Only-Costly-Observable MDPs AAAI, Vancouver, Canada, July 24
- 2007 A Reinforcement Learning Algorithm with Polynomial Interaction Complexity for Only-Costly-Observable MDPs

BISFAI, Ramat Gan, Israel, June 21

Departmental Talks

- 2022 Curiously Effective Ensemble and Double-Oracle Reinforcement Learning Methods CML Seminar, University of California, Irvine, January 10
- 2020 When "Optimal Control" Isn't
 - CS Seminar, University of California, Irvine, November 20
 IMBS Seminar, University of California, Irvine, April 17
- 2019 Hierarchical Imitation Learning of Robot Skills and Control Programs
 - RISE Retreat, University of California, Berkeley, January 17
- 2018 Multi-Task Hierarchical Imitation Learning of Robot Skills
 - BAIR/CPAR/BDD Seminar, University of California, Berkeley, October 12
 RISE Seminar, University of California, Berkeley, October 8
- 2018 SkillHub: Shared Hierarchical Imitation Learning of Robot Control RISE Retreat, University of California, Berkeley, May 23
- 2018 Parametrized Hierarchical Procedures for Neural Programming RISE Retreat, University of California, Berkeley, January 10

| 2017 | Discovery of Hierarchical Structure for Robot Learning and Neural Programming |
|------|---|
| | BAIR/CPAR/BDD Seminar, University of California, Berkeley, November 3 |

- 2017 Reinforcement Learning Concepts RISE Camp, University of California, Berkeley, September 7
- 2017 Multi-Level Discovery of Deep Options
 - RISE–BDD Joint Mini-Retreat, University of California, Berkeley, May 2
 BAIR/CPAR/BDD Seminar, University of California, Berkeley, March 17
- 2017 Learning Control Hierarchies RISE Retreat, University of California, Berkeley, January 11
- 2015 Soft-Optimal Decisions under Uncertainty Machine Learning Club, Hebrew University, October 22
- 2013 Separating Inference and Control The Center for Theoretical Neuroscience, Columbia University, May 13
- 2013 What to Notice and What to Remember: Finding Good Inference Policies The Interdisciplinary Center for Neural Computation Retreat, Hebrew University, January 29
- 2012 Information Theory in Reinforcement Learning

The Center for Theoretical Neuroscience, Columbia University, August 20
 Neural Data Analysis Seminar, Columbia University, May 22

- 2012 Bounded Planning in Passive POMDPs Machine Learning Club, Hebrew University, March 15
- 2007 Reinforcement Learning in Partially Observable Decision Processes

Graduate Seminar, Technion IIT, November 4

Advising and Mentoring

Postdocs

2024-current Davide Corsi

PhD Students

| 2023-current | Armin Karamzade |
|--------------|---|
| 2022-current | Dmitry Krylov |
| 2021-current | Kyungmin Kim |
| 2021-current | Alexander Shmakov (advised by Pierre Baldi) |
| 2020-current | JB Lanier (jointly with Pierre Baldi) |
| 2020-current | Kolby Nottingham (jointly with Sameer Singh) |
| 2023-current | Undergraduate Students Montek Kalsi • Tony Liu • Yanran Wang |
| 2020 current | |
| 2019–2021 | PhD Alumni Stephen McAleer (advised by Pierre Baldi) → postdoc @ CMU |
| | Past Visitors |
| | Kat He \rightarrow MS student @ Columbia |
| | Bryan Yu $ ightarrow$ ShieldAl |
| 2021–2022 | Kevin Wang $ ightarrow$ PhD student @ Brown |

Master's Alumni

- 2022–2023 Alekhya Pyla \rightarrow Pinterest
- 2021–2022 Ankita Sinha \rightarrow Intuit
- 2020–2022 Dailin Hu \rightarrow Blizzard
- 2020–2022 Andrew Jiang \rightarrow Cisco
- 2020–2022 Alex Konrad (thesis) \rightarrow Spatial Genomics

Undergraduate Alumni

- 2022–2023 Sushrut Borkar
- 2022–2023 Isabel Rosen \rightarrow Microsoft
- 2022–2023 Zihao Zhu \rightarrow MS student @ UCLA
- 2021–2023 Yifei Liu \rightarrow MS student @ CMU
- 2021–2022 Xinyi Huang \rightarrow Circle
- 2021–2022 Junhan Ouyang \rightarrow DataVisor
- 2021–2022 Thomas Reeves \rightarrow MS student @ USC
- 2021–2022 Jiawen Zhang \rightarrow MS student @ UPenn
- 2020–2022 Litian Liang \rightarrow MS student @ UCSD
- 2020–2022 Yaosheng Xu \rightarrow MS student @ Harvard
- 2020–2021 Yongxuan Fu \rightarrow MS student @ Brown
- 2020–2021 Yao Luo \rightarrow MS student @ Columbia
- 2020–2021 Chinmay Tyagi \rightarrow MS student @ GeorgiaTech
- 2020–2021 Yinfei Wang \rightarrow Huawei
- 2020–2021 Ted Zadouri \rightarrow MS student @ UCLA \rightarrow PhD student @ Princeton
- 2019–2021 Carleton Zhao \rightarrow Amazon
- 2019–2020 Dailin Hu \rightarrow MS student @ UCI
- 2019–2020 Mingen Li \rightarrow MS student @ UCSD
- 2019–2020 Bryon Tjanaka \rightarrow PhD student @ USC
- 2019–2020 Catherine Yuan \rightarrow General Atomics Aeronautical
- 2018–2019 William Paul \rightarrow Johns Hopkins University Applied Physics Lab
- 2018–2019 Matthew Trepte \rightarrow Nvidia
- 2018–2019 Andy Yan \rightarrow MS student @ Berkeley
- 2018–2019 Yitian Zou \rightarrow Uber
- 2017–2018 David Tseng \rightarrow Microsoft
- 2014–2015 Itay Fried \rightarrow Applied Materials
- 2014–2015 Erez Peterfreund \rightarrow MS student @ Hebrew University $\rightarrow \cdots \rightarrow$ postdoc @ Yale

Teaching

Instruction

- CS 2005 Seminar in Computer Science Research, Computer Science, UC Irvine ☑ Departmental seminar organizer; Fall 2021 – Spring 2024
- CS 277 **Control and Reinforcement Learning**, *Computer Science*, UC Irvine Winter 2020 🗹 Winter 2021 🗹 Winter 2022 🗹 Winter 2024 🗹

- CS 273A Machine Learning, Computer Science, UC Irvine Winter 2021 ☑ • Fall 2021 ☑
 - CS 175 **Project in Artificial Intelligence**, *Computer Science*, UC Irvine Winter 2020 ☑ Fall 2021 ☑
 - 76929 **Reinforcement Learning**, *Center for Brain Sciences*, Hebrew University Winter 2014 ☑ Winter 2015

Guest Lectures

- Fall 2020 AI/ML for Computational Science (CS 295), Computer Science, UC Irvine
- Fall 2019 Honors Seminar (CS H197), Information and Computer Science, UC Irvine

Professional Service

Workshop Organizer

- 2024 Heuristics and Search for Domain-independent Planning (HSDIP @ ICAPS) Co-organizers: Sofia Lemons, Daniel Gnad, Clemens Büchner, Imène Ait Abderrahim
- 2018 Infer to Control: Probabilistic Reinforcement Learning and Structured Control workshop (Infer2Control @ NeurIPS) ☑

Co-organizers: Leslie Kaelbling, Martin Riedmiller, Marc Toussaint, Igor Mordatch, Tuomas Haarnoja; estimated attendance: 650+

2017 Hierarchical Reinforcement Learning workshop (HRL @ NeurIPS) 🗹

Co-organizers: Andrew Barto, Doina Precup, Shie Mannor, Tom Schaul, Carlos Florensa; estimated attendance: 950+

Outreach

2021 UCI End Racism Initiative

Work group on Representation: Recruitment and Outreach to Black Students

Senior Program Committee Member / Meta-Reviewer

- 2024 IJCAI conference
- 2023 IJCAI conference NeurIPS conference
- 2022 ICML conference NeurIPS conference
- 2021 IJCAI conference
- 2020 IJCAI conference
- 2019 UAI conference

Session Chair / Moderator

- 2023 ITA workshop, Game Theory session chair
- 2022 ICML conference, Reinforcement Learning session chair
- 2022 NeurIPS conference, session chair
- 2021 IJCAI conference, Deep Reinforcement Learning session chair
- 2019 CASE conference, Service Robots session co-chair
- 2018 Infer2Control @ NeurIPS workshop, panel moderator
- 2017 HRL @ NeurIPS workshop, panel moderator
- 2016 CDC conference, Information Theory and Control session co-chair

Proposal Reviewer

- 2021 NSF CISE NSF FRR
- 2020 CEREC ISF NSF CISE
- 2019 AI XPRIZE competition technical judge

Program Committee Member / Reviewer

- 2022 Journals: IEEE-TAC Conferences: DeepMath RLDM
- 2021 Journals: IEEE-TAC JMLR Conferences: ICRA NeurIPS
- 2020 **Journals:** Artificial Intelligence JMLR **Conferences:** AAAI CDC DeepMath • IROS • RSS
- 2019 Journals: IJRR JAAMAS Conferences: CASE ICML ICRA IJCAI NeurIPS RLDM Workshops: HILL @ ICML OPTRL @ NeurIPS SPiRL @ ICLR
- 2018 Journals: Adaptive Behavior IJRR JAAMAS Conferences: ICLR ICML • NeurIPS • RSS • Workshops: Infer2Control @ NeurIPS
- 2017 Conferences: ICLR NeurIPS RSS Workshops: HRL @ NeurIPS
- 2016 Conferences: NeurIPS